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## Maxim Integrated Products and Linear Technology Corporation Settle Law Suit

Maxim Integrated Products and Linear Technology Corporation have settled their patent litigation that commenced on August 13, 1993. While both parties have agreed to keep specific terms of the settlement confidential, the agreement provides for cross licenses for existing patents in the RS-232 interface area, with Linear paying a nominal paid-up license fee. Maxim will not use Linear patents relating to step-down switching regulators, and will discontinue using the LTC product name prefix.

## 1995 New Releases Data Book



Maxim's 1995 New Releases Data Book introduces over 130 analog products-all released within the last year. This catalog of new data sheets guides you through your design with detailed specifications and applications information on the latest analog solutions. This book will be mailed by October 30, 1994 in the U.S.


## Pentium ${ }^{\text {TM }}$, PowerPC ${ }^{\text {TM }}$ Power Supply <br> Evaluation Board

This fully assembled evaluation board is available from Maxim. Among other applications, it assists in evaluating the circuits of Figures 5 and 6 in the following article.

## Power supplies for Pentium ${ }^{\text {TM }}$, PowerPC ${ }^{\mathrm{TM}}$, and beyond

The latest microprocessors to emerge from Intel, Motorola, and others are forcing fundamental changes in the power supplies for desktop and portable computers. Not only do the $\mu P s$ demand lower and more precise supply voltages, but their main clocks also exhibit start/stop operation that causes ultra-fast load transients. As a result, the relatively simple $5 \mathrm{~V} / 12 \mathrm{~V}$ supply has been transformed into a system with five or more outputs, featuring unprecedented accuracy and 50A/ $\mu$ s load-current slew rates.
These characteristics present a problem: it appears that the classic, centralized power-supply architecture cannot provide the accuracy and transient response needed by coming generations of computer systems. The more effective approach will be a distributed architecture in which local, highly efficient dc-dc converters are located on the motherboard next to the CPU. Expect power-supply manufacturers to respond with smaller, higher-frequency ICs and modules that feature improved dynamic response and better synchronous rectifiers. The PC's offline (silver box) power supply won't disappear; it will remain to generate the main bus for small dc-dc converters on the motherboard.

This article examines the power-supply architectures proposed for next-generation computers, and takes a close look at solutions for the problems currently facing designers of board-level computers.

## Voltage proliferation

The most significant trend associated with CPU power supplies is that of lower and lower supply voltages. The race downward to new voltage levels proceeds in jumps, as each major CPU manufacturer brings successive new fab processes on line. Currently, the lowest voltage mentioned around Maxim is 1.1 V -rumored as the $\mathrm{V}_{\mathrm{CC}}$ required for certain CPUs yet to be released.

It seems likely that core-logic chips, which will probably make use of the fab capacity vacated by CPUs as they graduate to finer-lithography fabs, will follow the CPUs in supply voltage. DRAM voltages, on the other hand, will
probably remain at 3.3 V for some time to come because of the large investments in 3.3 V fabs. Five volts should remain for a long time as well, even if used only to support audio and the existing customer base for PCMCIA cards and other 5 V -only peripherals. The result is a list of likely voltages (Table 1) that apply to ICs ranging from the present to more than a year away.

## Table 1. Current and projected operating voltages

| Supply | Imminent | 1.5 <br> Years Out | $\mathbf{3}$ <br> Years Out |
| :--- | :---: | :---: | :---: |
| CPU | $2 . \mathrm{XV}$ | 2.5 V or less | $1 . \mathrm{XV}$ |
| Core Logic | 3.3 V | 3.3 V | $2 . \mathrm{XV}$ |
| DRAM | 3.3 V | 3.3 V | 3.3 V |
| I/O and Analog | 5 V | 5 V | 5 V |
| PCMCIA, ISA 12V | 12 V | 12 V | $?$ |
| Bus Termination | none | 1.5 V | 1 V |
| Total Supply <br> Voltages | 4 | 5 | $5-6$ |

In addition to the standard CPU, I/O, and core-logic supplies, future systems will need a power supply for terminating high-speed data buses such as the 66 MHz Gunning Transceiver Logic (GTL) bus (Figure 1). Invented by Bill Gunning at Xerox, it consists of 144 or more open-drain transistor drivers, each with a $50 \Omega$ resistive pull-up to a low-voltage source (typically 1.5 V ).

## Special CPU voltages

In addition to the trend toward lower voltages, another factor is proliferating the levels of supply voltage: the tendency for manufacturers to specify special levels for certain models or clock-speed variants of a given CPU. This "voltage du jour" practice, conducted to enhance manufacturing yields at high clock speeds, includes 4 V (Cyrix), 3.6V (Power PC), and 3.45V (Intel).

A good example of special supply voltage is the "VR" version of Intel's P54C Pentium, which requires a supply voltage between 3.30 V and 3.45 V including noise and transients. This spec gives headaches to power-supply designers, who must worry about noise, transient response, and the minute voltage drops in connectors and wiring, as well as fundamental dc accuracy. Their complaints about layout difficulty and extra cost, however, are rightly outweighed by savings in the CPU itself. Paying $20 \%$ less for a $\$ 500 \mathrm{CPU}$ can finance a lot of power-supply stuff, so don't expect CPU makers to avoid non-standard supply levels-especially for their latest and "hottest" models.


Figure 1. This highly accurate, 1.5 V step-down dc-dc converter powers the termination resistors in a Gunning Transceiver Logic (GTL) bus. The converter's architecture—buck topology with synchronous rectifier-is by far the best choice for low-voltage, high-efficiency distributed power systems.

## Cross-regulation error

Another challenge for power-supply designers is crossregulation error-the variation at one regulated output caused by load-current variation at another-which is common in classic, low-cost, multi-output offline supplies. This error, produced in "green PCs" governed by load-switching power-management techniques, is actually caused by a power-saving measure-the absence of minimum loads on the regulated outputs.

The standard low-cost power supply for PCs generates multiple output voltages by including extra transformer windings on a flyback or forward off-line supply. A minimum load on the main output is necessary for maintaining regulation on the secondary outputs. But, this technique causes problems in the new computers (Green PCs ), which employ load-switching and clock-halting schemes to reduce power consumption. The resulting wild fluctuations of load current at each output can produce severe cross-regulation errors in conventional supplies. Along with fast load transients and tight output-accuracy specs, the cross-regulation problem is one reason why future systems will probably adopt a distributed powersupply architecture.

Another reason is parasitic inductance in the high-current paths. For systems in which the CPU clock starts and stops abruptly, even a few inches of wire contributes enough inductance to cause excessive ringing or sagging (or both) at the $\mathrm{V}_{\mathrm{CC}}$ pins. For the many cases in which IR drops and unwanted inductance completely rule out a centralized power supply, you must adopt a distributedpower architecture. It usually consists of small, local dcdc converters or linear regulators on the CPU motherboard, fed with 5 V or 12 V from the familiar silver-box power supply in the PC.

Once you decide on a distributed architecture, the next step is to decide between linear and switch-mode regulators. The issue is usually clear-cut: if you can tolerate the heat and efficiency loss, go with a linear supply; if not, choose a switch-mode supply with a step-down (buck) topology. Future desktop systems will probably distribute a power bus of 5 V or 3.3 V (or both), and generate the lower CPU voltages with local linear regulators (Figures 2 and 3). Portable systems, in which efficiency is always paramount, often distribute their battery voltage to switch-mode converters located on the motherboard.


Figure 2. This linear-regulator circuit includes a fast, low-power op amp for excellent dynamic response to fast-load transients caused by the latest dynamic-clock CPUs. The low-threshold, p-channel MOSFET (vs. a bipolar transistor) provides an ultra-low dropout voltage and minimum quiescent current.

Linear regulators cost $\$ 2$ to $\$ 3$, vs. $\$ 6$ to $\$ 7$ for a switchmode type. Faster loop response lets the linear types handle load transients with less output capacitance. And in many cases, the linear regulator's efficiency is acceptably high even for portable applications.

Discounting the losses due to quiescent and base currents, the efficiency of a low-dropout linear regulator equals $\mathrm{V}_{\mathrm{OUT}} / \mathrm{V}_{\text {IN }}$. A 5 V -to- 3.3 V converter, for example, has an efficiency of $66 \%$-which means that a maximum load of 3 A will produce 5 W of heat dissipation. That amount of power is easily handled with a heatsink, but for multiprocessor LAN servers with four or more CPUs, the required dissipation jumps to 20 W . That power level is hard to disperse in a system that is already blazing hot. For 5V-to-3.3V desktop systems, the load-current crossover point at which heatsinking problems outweigh the extra cost of a switch-mode supply is about 5A.
Step-down switching regulators exhibit typical efficiencies of $90 \%$ or better, almost independently of $\mathrm{V}_{\mathrm{IN}}$. But, compared with linear regulators they are more expensive, require a more careful pc layout, and generate more ripple and EMI. The classic buck topology (Figure 4) is by far the best choice; it is simple, has very high efficiency, and has the smallest magnetic components of all the competing topologies (forward, flyback, Cuk, etc.). Buck regulators are also compatible with synchronous rectifiers-a feature of increasing importance as CPU voltages fall, causing the power loss in a forward-biased rectifier to become a larger portion of the output power.


Figure 3. For systems in which 5V is unavailable for the op amp, this stand-alone linear regulator operates entirely from the 3.3 V bus, generating 2.9 V with only a minor degradation in transient response.

## Low-voltage, high-accuracy supplies

At lower levels of supply voltage, the logic swings decrease and produce a corresponding shrinkage in noise margins. Power supplies for future systems must therefore have very good dc and ac accuracy to avoid noise-margin problems. A $5 \%, 1.5 \mathrm{~V}$ supply, for instance, has an output tolerance of just $\pm 75 \mathrm{mV}$. Small voltage drops across the resistance of a connector, power-MOSFET switch, or wiring harness can so degrade accuracy as to render this supply unusable.

The dominant term affecting overall accuracy in a power supply is that of the internal reference-voltage accuracy. Reference accuracy is therefore a key parameter in power-supply ICs for the next generation of low-voltage systems. The question for IC designers is, how much manufacturing cost do you allow for the reference? The issue is not so much silicon area as the cost of laser trimming, testing, and yields.
The reference in today's typical power-supply IC represents $20 \%$ to $25 \%$ of the IC's manufacturing cost, and has a $\pm 2 \%$ output tolerance. The $\pm 2 \%$ error band allows the manufacturer to test at room temperature only, and screen for temperature extremes by sample testing only. But at $\pm 0.5 \%$, all the parts must be tested over temperature, and the the laser trimming must be more precise. Costs increase accordingly. Thus, the decision to include a precision, data-acquisition-grade reference in a powersupply IC is not to be made lightly.

Two circuit configurations provide high-accuracy supply voltages, each with a different tradeoff between cost and


Figure 4. This step-down (buck) switching regulator employs all nchannel MOSFETs to save cost, and operates at 300 kHz to minimize the physical size of its inductor.
accuracy (Figures 5 and 6). Both reduce the load-regulation error (to $0.1 \%$ ) by increasing the dc-loop gain with an external integrator amplifier (MAX495). The first circuit achieves low reference error with a screened ("T" grade) version of the MAX767, whose reference tolerance is $\pm 1.2 \%$ maximum. This Pentium P54C-VR application circuit is available from Maxim as an evaluation kit. The second circuit achieves still lower error with an external reference (MAX872), whose contribution to output uncertainty is only $\pm 0.38 \%$ over temperature.

Both circuits have low output ripple and excellent dynamic response. Step changes from zero to full load produce output excursions of less than 40 mV . In particular, each circuit supports the VR (voltage regulator) version of Intel's P54C Pentium CPU, whose supply voltage (including noise and transients) must remain between 3.30 V and 3.45 V . Table 2 lists the components recommended for different levels of output current in these two circuits.

Note: To prevent over-voltage at the CPU when the remote-sense line connects at the far side of a connector (which could be disconnected during supply operation), connect $10 \mathrm{k} \Omega$ from the sense line to the connector's near (power-supply) side.
(Circle 1)
Table 2. Component recommendations for Figures 5 and 6

| Part | 1.5A Circuit | 3A Circuit | 5A Circuit | 7A Circuit | 10A Circuit |
| :---: | :---: | :---: | :---: | :---: | :---: |
| L1 | $10 \mu \mathrm{H}$ <br> Sumida CDR74B-100 | $5 \mu \mathrm{H}$ <br> Sumida CDR125 <br> DRG\# 4722-JPS-001 | $3.3 \mu \mathrm{H}$ <br> CoilCraft DO3316-332 | $2.1 \mu \mathrm{H}, 5 \mathrm{~m} \Omega$ <br> Coiltronics CTX03-12338-1 | $1.5 \mu \mathrm{H}, 3.5 \mathrm{~m} \Omega$ Coiltronics CTX03-12357-1 |
| R1 | $0.04 \Omega$ <br> IRC LR2010-01-R040 or Dale WSL-2512-R040 | $0.02 \Omega$ <br> IRC LR2010-01-R020 or Dale WSL-2512-R020 | $0.012 \Omega$ <br> Dale WSL-2512-R012 <br> or $2 \times 0.025 \Omega$ <br> IRC LR2010-01-R025 <br> (in parallel) | $3 \times 0.025 \Omega$ <br> IRC LR2010-01-R025 <br> or Dale WSL-2512-R025 <br> (in parallel) | $3 \times 0.020 \Omega$ <br> IRC LR2010-01-R020 <br> or $2 \times 0.012 \Omega$ <br> Dale WSL-2512-R012 <br> (in parallel) |
| $\begin{aligned} & \mathrm{N} 1, \\ & \mathrm{~N} 2 \end{aligned}$ | International <br> Rectifier IRF7101, <br> Siliconix Si9936DY <br> or Motorola MMDF3N03HD <br> (dual n-channel) | Siliconix Si9410DY, <br> International <br> Rectifier IRF7101 <br> or Motorola MMDF3N03HD <br> (both FETs in parallel) | Motorola <br> MTD20N03HDL | Motorola <br> N1: MTD75N03HDL <br> N2: MTD20N03HDL | Motorola <br> MTD75N03HDL |
| C1 | $\begin{aligned} & 47 \mu \mathrm{~F}, 20 \mathrm{~V} \\ & \text { AVX TPSD476K020R } \end{aligned}$ | $\begin{aligned} & 2 \times 47 \mu \mathrm{~F}, 20 \mathrm{~V} \\ & \text { AVX TPSD476K020R } \end{aligned}$ | $220 \mu \mathrm{~F}, 10 \mathrm{~V}$ <br> Sanyo OS-CON 10SA220M | $2 \times 100 \mu \mathrm{~F}, 10 \mathrm{~V}$ <br> Sanyo OS-CON 10SA100M | $\begin{aligned} & 2 \times 220 \mu \mathrm{~F}, 10 \mathrm{~V} \\ & \text { Sanyo } \\ & \text { OS-CON 10SA } 220 \mathrm{M} \end{aligned}$ |
| C2 | $220 \mu \mathrm{~F}, 6.3 \mathrm{~V}$ <br> Sprague 595D227X06R3D2B | $2 \times 150 \mu \mathrm{~F}, 10 \mathrm{~V}$ <br> Sprague 595D157X0010D7T | $2 \times 220 \mu \mathrm{~F}, 10 \mathrm{~V}$ <br> Sanyo OS-CON 10SA220M | $2 \times 220 \mu \mathrm{~F}, 10 \mathrm{~V}$ <br> Sanyo OS-CON 10SA220M | $4 \times 220 \mu \mathrm{~F}, 10 \mathrm{~V}$ <br> Sanyo OS-CON 10SA220M |
| D2 | 1N5817 <br> Nihon EC10QS02, or Motorola MBRS120T3 | 1N5817 <br> Nihon EC10QS02, or Motorola MBRS120T3 | 1N5820 <br> Nihon NSQ03A02, or Motorola MBRS340T3 | 1N5820 <br> Nihon NSQ03A02, <br> or Motorola <br> MBRS340T3 | 1N5820 <br> Nihon NSQ03A02, or Motorola MBRS340T3 |
| Temp. <br> Range | to $+85^{\circ} \mathrm{C}$ | to $+85^{\circ} \mathrm{C}$ | to $+85^{\circ} \mathrm{C}$ | to $+85^{\circ} \mathrm{C}$ | to $+85^{\circ} \mathrm{C}$ |



Figure 5. This high-precision, step-down dc-dc converter is intended for Pentium P54C-VR desktop applications with stringent requirements for dc and ac accuracy. An evaluation kit for this Pentium VR application is available to speed designs (see page 2).


Figure 6. Otherwise similar to the step-down converter of Figure 5, this circuit adds a data-acquisition-grade voltage reference to further improve dc accuracy.

## New ICs <br> boost video performance

By integrating the functions once implemented with discrete components, new video ICs are making life easier for the design engineer (Table 1). The new products not only cost less and save space on the pc board, they offer better performance because the proximity of video functions on the IC reduces parasitic capacitance and its detrimental effect on bandwidth and other parameters. This article introduces basic video technology along with new, state-of-the-art video switches and their applications.

Switching is a common requirement in video systems. Video editors must select one of several input signals on command, and other systems (broadcast studios, security and surveillance networks) must be capable of displaying multiple input signals on multiple monitors.

Traditional video switches are followed by a buffer amplifier in a separate package. Some applications include an input buffer as well, to isolate the signal sources and preserve bandwidth (Figure 1a). The resulting circuits require at least two or three packages, but recent video-switch ICs have absorbed the output buffer while precluding the need for an input buffer. This integration of functions lowers the package count to one, and by minimizing certain parasitic capacitances it also improves the electrical performance.

## Monolithic vs. discrete switch/buffers

Distributed capacitance associated with the package, board, and switch make bandwidth preservation a difficult job in the traditional, discrete-IC video switch (Figure 1b). Switch capacitance $\mathrm{C}_{\mathrm{DS}}$ causes feedthrough that reduces OFF isolation. $\mathrm{C}_{\mathrm{pb}}$ and $\mathrm{C}_{\mathrm{pp}}$, also associated with the switch, combine with source impedance $\mathrm{R}_{\text {SOURCE }}$ (usually $75 \Omega$ ) to produce a bandwidth-limiting pole. The finite source impedance also causes $\mathrm{C}_{\mathrm{pp}}$ to produce coupling (crosstalk) between the two channels. Adding an input buffer as shown in Figure 1a eases the effect on bandwidth and crosstalk by substituting a low impedance for $\mathrm{R}_{\text {SOURCE }}$.
Referring again to Figure 1b, note that the switch output capacitance consists of $\mathrm{C}_{\mathrm{pb}}$ and $\mathrm{C}_{\mathrm{CM}}$ in parallel, plus a differential-mode value $\left(\mathrm{C}_{\mathrm{DM}}\right)$ between the pins. These


Figure 1. For a traditional video switch, the switch and buffers reside in separate ICs (a). Parasitic capacitances in the traditional switch limit bandwidth and provide paths for unwanted feedthrough and crosstalk (b). The integrated approach (c) improves performance by minimizing parasitics.
capacitances charge rapidly when the switch closes (turns on), but they discharge through a rapidly increasing switch resistance when the switch turns off. The resulting slow turn-off can produce unwanted artifacts at the boundary between images in a graphics display.

Table 1. Video/High-Speed Products

$\dagger$ Prices provided are for design guidance and are FOB USA. International prices will differ due to local duties, taxes, and exchange rates.
$\dagger$ Future product-contact factory for pricing and availability. Specifications are preliminary.

Switch on-resistance must be low enough to prevent distributed capacitance from limiting the signal bandwidth. A $75 \Omega$ switch with 10 pF , for example, produces a rolloff to -3 dB at $1 / 2 \pi \mathrm{RC}=212 \mathrm{MHz}$. But, switches with low on-resistance are physically large structures with unavoidably large values of junction capacitance $\mathrm{C}_{\mathrm{DG}}, \mathrm{C}_{\mathrm{DS}}$, and $\mathrm{C}_{\mathrm{SG}}$. $\mathrm{C}_{\mathrm{DS}}$ undermines the isolation between source and output, and the other parasitics undermine the bandwidth. An input buffer can compensate for these effects, but (as mentioned) it adds a third package to the circuit.
The integrated approach combines switch and buffer in one package (Figure 1c). The switch can have higher on-resistance because the switch-to-amplifier capacitances $\left(\mathrm{C}_{\mathrm{pb}}\right.$, $\mathrm{C}_{\mathrm{M}}$, and $\mathrm{C}_{\mathrm{D}}$ ) are smaller. In turn, the higher-resistance switch is physically smaller, and its lower-valued $C_{D G}$, $\mathrm{C}_{\mathrm{DS}}$, and $\mathrm{C}_{\mathrm{SG}}$ may eliminate the need for an input buffer. As a further advantage, switching transients and other performance parameters are specified for the switch/buffer combination as a single subsystem. Integration thus improves performance while saving board space.

## Circuit topology

A major concern in multiplexing video signals is the degree of isolation between the output and the non-selected input signals. Data sheets specify this isolation as "adjacentchannel crosstalk" and "all-hostile crosstalk." Integrated multiplexer-amplifiers perform well in this respect-most such devices provide isolation in excess of -60 dB , which is sufficient for most NTSC and PAL systems.
A popular method for providing high isolation is the " T " switch (Figure 2a). Used in all CMOS "mux-amps" from Maxim, the T-switch preserves isolation by shorting to ground the feedthrough capacitance of S 1 : when the Tswitch is on, S 1 and S 3 are closed and S 2 is open; when the T-switch is off, S1 and S3 are open and S2 is closed. Thus, signals that would otherwise couple through $\mathrm{C}_{\mathrm{S}}$ are shorted to ground before reaching the output. The disad-vantage-higher on-resistance due to S1 and S3 in series-is usually not a problem for the IC because intrachip capacitances at the output of S3 can be kept very low.
An implementation of the T-switch in bipolar technology includes parallel npn transistors on one side of the buffer amplifier's differential input pair (Figure 2b). Turning on Q3 steers emitter current from Q1 and robs Q5 of base current. Q1 and Q5 turn off, disconnecting IN0 from the output stage. This action is similar to that of the T-switch, in which two off transistors (Q1 and Q5) are shorted to ground via Q3.


| VIDEO <br> T-SWITCH | S1 | S2 | S3 |
| :---: | :---: | :---: | :---: |
| ON | ON | OFF | ON |
| OFF | OFF | ON | OFF |

(b)

(c)


Figure 2. By shunting feedthrough currents to ground (through S2), the $T$-switch provides improvements of $6 d B$ to $12 d B$ in feedthrough and crosstalk (a). Implemented in bipolar technology, the $T$-switch configuration offers high input impedance and low input capacitance (b). Make-beforebreak action in the integrated $T$-switch minimizes glitches (c).

## Definitions

"Video" in this article refers to the approximate $4 M H z$ to $6 M H z$ analog signals that emanate from a video camera-i.e., baseband video in the context of broadcast television. "Graphics" refers to the resulting CRT display. (Note that the video signals for high-performance workstations and other graphics systems, generated by a computer and reconstructed with a D/A converter, can exceed 100 MHz .) Other video terms are defined as follows:

NTSC (National Television Standards Committee) is the US agency that developed standard monochrome and composite-color waveforms for the US. NTSC signals are now used in the US, Japan, Canada, Mexico, and many other countries of the western hemisphere. Because these systems are sensitive to errors of differential gain and phase, Europeans once referred to NTSC as "Never The Same Color." Today's high-performance circuits have largely eliminated these problems.
PAL (Phase Alternate Line) is a transmission standard for color television developed by the Telefunken Company in Germany, partly as an answer to the shortcomings of NTSC. Though similar to NTSC, it includes a line-by-line alternation in phase for one of the two color-signal components, which minimizes the distortion due to differential phase error between the luminance and chrominance signals. PAL is used by the United Kingdom and most of Western Europe, except France.

SECAM (Sequential Couleur Avec Memoire) was developed in France, also as an alternative to NTSC. Luminance signals have the same format as those of NTSC and PAL, but the color-difference signals modulate two separate carriers that are transmitted on alternate lines. To restore the missing color information for a given line, SECAM receivers include a one-line memory element ( 1 H delay). Today, SECAM is used in France and in some countries of the former USSR.

IRE (Institute of Radio Engineers) was a forerunner of today's IEEE. Today, the term represents an arbitrary unit for measuring relative amplitudes on a video signal. One hundred IRE units represents full scale (i.e., 1 V on a monochrome signal or 0.714 V on a color signal).

RGB (Red, Green, Blue) is a term that refers to the primary colors. A video camera resolves light into its RGB components and generates the corresponding analog voltages $\mathrm{E}_{\mathrm{R}}, \mathrm{E}_{\mathrm{G}}$, and $\mathrm{E}_{\mathrm{B}}$. After gamma correction (which minimizes the visual effect of noise by assuring a logarithmic relation between signal amplitude and CRT brightness) the signals become $\mathrm{E}_{\mathrm{R}}{ }^{\prime}, \mathrm{E}_{\mathrm{G}}{ }^{\prime}$, and $\mathrm{E}_{\mathrm{B}}{ }^{\prime}$. These are encoded to produce the luminance component " $\mathrm{E}_{\mathrm{Y}}$ " $\left(0.30 \mathrm{E}_{\mathrm{R}}{ }^{\prime}+0.59 \mathrm{E}_{\mathrm{G}^{\prime}}+0.11 \mathrm{E}_{\mathrm{B}}\right.$ '), and the chrominance components " $\mathrm{E}_{\mathrm{U}}$ " ( $\mathrm{E}_{\mathrm{R}}$ ' $-\mathrm{E}_{\mathrm{Y}}$ ) and " $\mathrm{E}_{\mathrm{V}}$ " ( $\mathrm{E}_{\mathrm{B}}$ ' $-\mathrm{E}_{\mathrm{Y}}$ ).

Component video refers to individual signal components such as the three found in an RGB or YUV system.
Composite video is an analog waveform suitable for transmission on a single channel. It is obtained by combining the chrominance and luminance signals with sync and blanking pulses.
Saturation is a term of perception (not subject to quantitative measurement) that refers to the intensity of a primary color. It corresponds to purity, which is an objective, measurable quantity.
Hue is a term of perception (not subject to quantitative measurement) that corresponds to a color's dominant wavelength, which is an objective, measurable quantity.
Color burst is a brief reference pulse of RF energy that is transmitted with every line of an NTSC signal. Because the color subcarrier (phase and amplitude modulated according to hue and saturation) and the color burst derive from the same signal, phase and amplitude distortion affect burst and subcarrier equally, and tend to cancel.

Differential gain and differential phase errors result from nonlinear characteristics in a video amplifier. Because the amplifier's gain and phase responses change slightly with signal level, variations in luminance affect the color subcarrier's gain and phase modulation. Differential gain error (DG) is a change in gain as the amplifier's dc output level swings from 0 V to 1 V , and differential phase error (DP) is a change in phase over the same range. DG (expressed in dB or \%) affects color saturation in the CRT display, and DP (expressed in degrees) affects the hue.

Similarly, turning off Q4 allows Q2 to act as an emitter follower, connecting IN1 to the output via Q6. The high input impedance and low input capacitance of this pnp emitter follower (Q2) negates the need for an input buffer amplifier. It also isolates the input signal from switching transients. The circuit's make-before-break action minimizes glitches (Figure 2c). Note that a break-beforemake action would open both switches at the same time, floating the inputs to the output stage and causing a highamplitude glitch as the output slews toward a supply rail.
Mechanical switches usually avoid make-before-break action, because shorting the inputs together would disrupt the signals on those channels (the signals may be routed to other destinations besides the switches). This problem can't occur with bipolar switches from Maxim, because each switch is preceded by an internal unity-gain buffer.
T -switches are found in integrated-circuit multiplexers as well as IC switches. Maxim's MAX442, for example, combines a 2PST switch with an uncommitted, unity-gain-stable output amplifier in an 8 -pin DIP or SO package. It switches one of two composite video signals to a single output, as required in a video editor or tape recorder. T-switches in the MAX442 assure -76dB minimum isolation and crosstalk, which is 6 dB to 12 dB lower than that of conventional switches.

## Composite video vs. RGB

In video systems, "RGB" refers to the three electrical signals corresponding to the red, green, and blue components of an image. After correction and shaping, the RGB signals are encoded to produce chrominance (color) and luminance (brightness) signals. Then, combining the chrominance and luminance with sync and blanking signals produces a "composite" video signal (see sidebar). Thus, combining all video information in a single signal makes a convenient input for monitors, VTRs, and broadcast transmitters.
Composite signals allow single-channel transmission (especially convenient for broadcasting), but their complex encoding of chrominance and luminance information carries disadvantages. System nonlinearities, for instance, degrade the image by producing unavoidable crosstalk between the luminance and chrominance components. To control this problem, engineers seek to develop signal-processing electronics with minimal errors of differential gain (which affects color saturation) and differential phase (which affects hue).
Video signals in a broadcast studio may pass through many stages of editing and recording. To maintain
fidelity in these applications, the studio video is best handled in a three-signal "component" format that eliminates the use of subcarriers with their crosstalk and noise problems. The original RGB can serve as component video, but advantages are realized by encoding RGB as YUV-i.e., the electrical analogs of luminance (Y) and the color differences B-Y (U) and R-Y (V) (see sidebar).

YUV requires less bandwidth than RGB: Equal amounts of picture detail reside in R, G, and B, but the YUV system conveys fine picture detail only in Y ( U and V carry color information only). Bandwidths are approximately 4.2 MHz for $\mathrm{Y}, 0.5 \mathrm{MHz}$ for U , and 1.5 MHz for V , resulting in a lower overall bandwidth that can save costs. A video tape recorder, for example, needs three tracks to handle RGB video. For YUV, the VTR requires only two tracks-one for Y and one for U and V together.
YUV components have another advantage-the U and V signals are less subject to electronic gain error than are the RGB signals. Gain error in one RGB channel produces a wrong-colored image; gain error in the U or V channel produces only a small change in hue or saturation.
Many video cameras provide RGB outputs in addition to a composite output, and some commercial television monitors provide RGB inputs in addition to the composite input. YUV components are easily derived from RGB components with a resistive network called a matrix circuit.

## Video editors

The substitution of video ICs for discrete-component circuitry, plus the growing importance of video for teleconferencing and related applications, has produced an expanding market for video ICs. One target for these products is the video editor.

Video editors accept one or more signals, which may be in different formats, from cameras, VTRs, computers, and other sources. After "editing" (rotating, translating, zooming, mixing, keying, wiping, etc.) the editor directs the signals to one or more VTRs or other systems. The video editor's electronics must pay close attention to dc as well as ac signal parameters.
In many cases, dc levels are unknown for the video editor's input signals. Each input, therefore, may include a dc-restore circuit that employs capacitive coupling to establish the zero (black) level. If this dc restoration is followed by switching, the subsequent amplifiers must have low dc offsets.

Two such devices-the MAX440 and MAX441 multiplexer/amplifiers (mux/amps)-illustrate the perfor-


Figure 3. These mux/amp ICs can be combined as shown to form larger multiplex arrays.
mance available with T-configuration switches. Each combines a unity-gain-stable, wideband output buffer with an 8-channel (MAX440) or 4-channel (MAX441) video multiplexer. The parts offer low input-offset voltages of $\pm 2.5 \mathrm{mV}$ typical ( $1 / 4 \mathrm{IRE}$ ), low values of differential gain and phase $\left(0.04 \%\right.$ and $0.03^{\circ}$ respectively), and low feedthrough and crosstalk ( -66 dB ).

The ICs' output-disable capability enables their use in larger multiplex arrays (Figure 3). Each EN input serves as a fourth address bit (A3), and the inverters insure that two amplifiers are not enabled simultaneously. With proper selection of the R1-R6 values you can add more MAX440s in parallel, up to a limit imposed by parasitic capacitance and feedthrough from the de-selected channels.

Each back-termination resistor (R1 and R4) has been increased from $75 \Omega$ to $80.6 \Omega$ to compensate for the three resistors at the output of the disabled amplifier. In parallel with R1 or R4, these resistors produce the desired $75 \Omega$ termination value. The three resistors also form a divider with the active amplifier's output resistor. To compensate for this effect, the closed-loop gain of each amplifier is set slightly greater than 6 dB . And to help minimize ringing, the amplifier outputs are joined at the cable end of R1 and R4-a connection that allows the resistors to isolate the enabled amplifier from the output capacitance of the disabled amplifier.

These circuits handle composite video, but many systems require switching of component video signals. To meet that need, Maxim has introduced the first switch/buffer ICs for RGB, YUV, YRGB, or RGB+SYNC applications (Table 2). MAX463-MAX466 devices switch from two sets of three inputs to one set of three outputs (3P2T) or from two sets of four inputs to one set of four outputs (4P2T). Each device contains an output driver with a fixed gain of one or two, which is capable of driving $\pm 2 \mathrm{~V}$ into a $75 \Omega$ back-terminated cable ( $150 \Omega$ load). And for buffering RGB, YUV, or other component video, the MAX467-MAX470 series includes triple and quad buffer amplifiers without the switches.

## Table 2. Video switch/buffer ICs

| Device | Description | Voltage <br> Gain |
| :--- | :--- | :---: |
| MAX463 | Triple switch \& buffer | 1 |
| MAX464 | Quad switch \& buffer | 1 |
| MAX465 | Triple switch \& buffer | 2 |
| MAX466 | Quad switch \& buffer | 2 |
| MAX467 | Triple video buffer | 1 |
| MAX468 | Quad video buffer | 1 |
| MAX469 | Triple video buffer | 2 |
| MAX470 | Quad video buffer | 2 |

The output buffers provide a combination of isolation and bandwidth that satisfies most video applications. By sandwiching each input and output pin between two acground pins, the devices hold adjacent-channel crosstalk to 60 dB at 10 MHz . Their 100 MHz bandwidths $(90 \mathrm{MHz}$ for gain-of-two buffers) and $200 \mathrm{~V} / \mu \mathrm{s}$ slew rates ( $300 \mathrm{~V} / \mu$ s for gain-of-two buffers) are difficult to achieve in discrete-component circuits. Wide bandwidth, low differential gain and phase error, and excellent gain and phase matching suit the MAX463-MAX470 devices for a wide range of component-video applications.


Figure 4. In the MAX463-MAX470 family of switch/buffer ICs, separate channels offer matched gain and phase over many megahertz of video bandwidth.

RGB video systems convey color information by amplitude only, so differential phase errors are unimportant. Gain and phase matching between channels, however, is important. Figure 4 shows typical gain and delay matching for the MAX463-MAX470 devices.
Many functions in a video editor are handled by highspeed digital circuits, which require close attention to layout issues such as power-supply decoupling and the minimization of ground and power-supply transients. See the last section (Layout, grounding, and bypassing) for guidance in these matters.

## Security and surveillance systems

Multiple inputs and outputs are a common feature of most security and surveillance systems, as is the need to make arbitrary connections between a given input and one or more outputs. Cost is a major issue for the "crosspoint switches" developed for this purpose.
Maxim is currently the only manufacturer of integrated crosspoint switches (Table 3). These devices really shine as space savers: a 16x16 array ( 16 inputs and 16 outputs) consisting of four MAX456 ICs (not including cable drivers) replaces 256 discrete switches and at least 32 buffer amplifiers. The same array constructed with MAX458 or MAX459 crosspoints requires eight packages, but those versions also include the cable drivers.

## Table 3. Maxim crosspoint switches

| Device | No. of <br> Switches | Technology | Gain | Differential <br> Phase/Gain | Cable <br> Driver |
| :---: | :---: | :---: | :---: | :---: | :---: |
| MAX456 | $8 \times 8$ | CMOS | 1 | $1.0 \% 0.5 \%$ | No |
| MAX458 | $8 \times 4$ | Bipolar | 1 | $0.5 \% 0.01 \%$ | Yes |
| MAX459 | $8 \times 4$ | Bipolar | 2 | $0.14 \% .13 \%$ | Yes |

MAX458 and MAX459 switches can be programmed either in parallel mode or in serial mode, which is fully compatible with SPI ${ }^{\mathrm{TM}}$, $\mathrm{QSPI}^{\mathrm{TM}}$, and Microwire ${ }^{\mathrm{TM}}$ standards for synchronous-data transmission. MAX458 and MAX459 outputs are disabled automatically at power-up. The disabled outputs assume a highimpedance state, except the MAX459's internal feedback (for achieving a gain of two) limits its output impedance to $1 \mathrm{k} \Omega$. Both devices can also be disabled on command, via software-a feature that enables the construction of switching arrays larger than $8 \times 4$.

## CRT drivers

Moving up from the crosspoint switch to the CRT, we find another target for integration in video systems-the high-voltage CRT driver for high-resolution monitors. A new, monolithic variable-gain amplifier (Figure 5a) drives these monitors directly. Its internal preamp and high-voltage output driver provide a reliable, low-cost, and space-saving alternative to hybrids and discretecomponent circuitry.

The IC's offset and variable-gain controls enable brightness and contrast adjustments. Its current-drive output provides for faster rise and fall times than those of a voltage-output device, and its TTL BLANK input disables the video signal by turning off the output current. The MAX445's 2.5 ns rise time through 50 V (Figure 5b) makes it ideal for driving the high-resolution displays ( $1280 \times 1024$ and $1530 \times 1280$ ) found in workstations and medical-imaging systems.

## Layout, grounding, and bypassing

Layout on the printed-circuit board is important for all analog circuits, but it is especially crucial for video and other high-speed circuitry. A choice of surface-mount over feedthrough components, for example, may seriously affect performance by altering the layout.

To realize the full ac performance specified for highspeed amplifiers, you should provide a large, lowimpedance ground plane and pay close attention to the pc layout and power-supply bypassing. Multilayer boards are preferred. Place an unbroken ground plane on a layer without signal traces, in a way that provides shielding for the traces. All inputs and outputs should be connected through lines of constant impedance, so you might consider a review of stripline techniques.
The input capacitance $\mathrm{C}_{\mathrm{IN}+}$ can limit the bandwidth in a buffer amplifier by forming a pole with the signal-source

[^0]Microwire is a trademark of National Semiconductor Corp.


Figure 5. The current-drive output in this high-voltage amplifier drives high-resolution CRT monitors directly, with rise and fall times of 2.5 ns .
impedance $\mathrm{R}_{\mathrm{S}}$. The pole can be defeated, however, by preventing current flow in $\mathrm{C}_{\mathrm{IN}+}$. Buffer operation maintains the $\mathrm{IN}+$, IN -, and OUT terminals at the same potential. Thus, surrounding IN+ with an ac "guard ring" driven by the buffer's output eliminates the current flow in $\mathrm{C}_{\mathrm{IN}+}$ by removing voltage variations across it. Adjacent positions for IN+, IN-, and OUT simplify the guard-trace layout (Figure 6).

You should bypass all power-supply pins directly to the ground plane with $0.1 \mu \mathrm{~F}$ ceramic capacitors placed as close to the pins as possible, and keep the lead lengths as short as possible to minimize series inductance. For high-current loads, it may be necessary to include $10 \mu \mathrm{~F}$ tantalum or aluminum electrolytic capacitors in parallel with the $0.1 \mu \mathrm{~F}$ ceramics. Surface-mounted chip capacitors are ideal for this application.

To prevent unwanted coupling of signals, minimize the trace area at the circuit's critical high-impedance nodes, and surround each analog input with ac-ground traces.


Figure 6. Surrounding this buffer amplifier's input (pin 2) with a guard ring driven by the output (pin 1) minimizes the effect of input capacitance on bandwidth.

The analog inputs and outputs of Maxim switches are separated with such ac-ground pins (GND, $\mathrm{V}_{\mathrm{CC}}$, and $\mathrm{V}_{\mathrm{EE}}$ ), which minimize the parasitic coupling that causes crosstalk and amplifier instability. To further reduce crosstalk, connect the coaxial-cable shield to the ground side of the $75 \Omega$ termination resistor, at the ground plane.

Wherever possible, use Faraday shields that interpose the ground plane or another component between sensitive circuits and those that produce noise. Noise generators include the digital circuitry that operates as an interface to the systems processor and memory.

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(Circle 2)

## DESIGN SHOWCASE

## Draw 150 mW of isolated power from off-hook phone line

The power supply of Figure 1 is useful in portable systems that connect to subscriber (household) telephone lines, such as modems and telephone test sets. For systems that require 150 mW or less, this circuit eliminates the need for batteries and ac adapters by drawing power from ordinary phone jacks without interrupting the voice signal. Built into peripheral equipment such as PCMCIA modem cards, it can spare the battery in a host computer.
The line current available to a telephone in the offhook state is limited not by regulations or code, but


Figure 1. This circuit draws current in the off-hook condition, delivering as much as 150 mW of isolated power while allowing normal voice or data communications over the phone line.
tions. Similarly, T1's turns ratio should provide the minimum-required output voltage for maximum load and minimum input voltage. This calculation should also assume worst-case losses in D2 and D3.

This turns ratio produces a much higher secondary voltage for best-case conditions, and for some applications that is acceptable. Otherwise, add the linear regulator (IC2) as shown. For isolated 5 V outputs, the ideal turns ratio is $1.2 \mathrm{CT}: 1.0 \mathrm{CT}$ ( $\mathrm{CT} \equiv$ Center Tapped). The transformer should be wound on Magnetics Incorporated "W," Fair-Rite "76," or other high-permeability magnetic material. To minimize radiated noise, choose a pot core, $\mathrm{E} / \mathrm{I} / \mathrm{U}$ core, toroid, or other geometry with closed magnetic paths.
Consider a typical toroid such as the 40603-TC from Magnetics, Inc. ( $0.125^{\prime \prime}$ thick with a $0.230^{\prime \prime}$ outside diameter). For 6.8 V inputs this core should have a 48-turn primary ( 24 turns on either side of the CT ), which yields a nominal, end-to-end primary inductance of 8 mH . The secondary can be scaled for any
reasonable output voltage required. Forty turns, for example, ( 20 turns on either side of the CT) delivers 5.2 V minimum as required by the linear regulator for maintaining a regulated 5 V output.

For isolated 3.3 V applications, the minimum voltage to IC 2 is 3.5 V . T1's turns ratio should be $2.0 \mathrm{CT}: 1.0 \mathrm{CT}$, with a primary ET product of at least $25 \mathrm{~V}-\mu \mathrm{s}$. Using the same 48 -turn primary as for 5 V applications, the required number of secondary turns is 24 ( 12 on either side of the CT). In addition, you must add a resistive divider for setting IC2's regulated output to 3.3 V .
Q1, Q2, and the associated resistors assure a lowpower shutdown mode for IC1 until its supply voltage can sustain a full power-up. IC1's supply current is fairly constant, so light filtering (provided by L1 and C3) is sufficient to prevent noise from entering the hybrid transformer (not shown).

A related idea appeared in the 9/1/94 issue of EDN.
(Circle 3)

## 12-bit ADC upgrades $\mu$ C's internal 8-bit ADC

The simple circuit of Figure 1 (plus a software routine) lets you substitute a multi-channel, 12-bit A/D converter for the 8-bit A/D converter internal to an 87C752 microcontroller. Thus, a single assembly can implement both the low- and high-performance versions of a system. The software mentioned may be downloaded from EDN's free electronic bulletin board service (BBS)*.
A socket lets you plug in the external A/D converter when you need it; otherwise you plug in the network of ten $10 \Omega$ resistors. At power-up, the $\mu \mathrm{C}$ executes a routine that looks for the external converter. If present, it is used; if not, the internal 8-bit converter is used. (Internally, the chip handles all conversion results as 12-bit values.)
This idea relies on the fact that the 87 C752's five A/Dinput pins can also serve as the bidirectional pins of an 8051 port (port 1). The resistor network connects the internal A/D converter directly to the applied analog inputs. Or, replacing the network with the external A/D converter connects those inputs to corresponding channels on that converter, and the $\mu \mathrm{C}$ 's $\mathrm{A} / \mathrm{D}$-input pins (now acting as a bidirectional port) serve as a digital interface to the converter. By fortune and design, the change from external to internal converter is effected by simple pin-for-pin jumpers across the socket.

The assembly-language software routine "looks" for the external converter by triggering a conversion and noting whether the converter's busy flag (SSTRB) goes low. If it does, the $\mu \mathrm{C}$ sets an internal global flag (AD12) that tells it to use its external-converter routines for each subsequent conversion. This action is transparent to the calling routine. The conversion result, returned as bytes ADHI and ADLO, has the same format in either case except the four LSBs are zero for 8-bit-converter data.
Note that the $\mu \mathrm{C}$ 's full scale is 5 V , but the converter shown (MAX186) sets its full-scale input range with an internal reference of 4.096 V . Software resolves the incompatibility in this example. Otherwise, you can replace the MAX186 with a MAX188 (a similar device with no internal reference) plus a separate 5 V reference.

* Set modem to 2400 baud, eight data bits, no parity, and one stop bit. Dial (617) 558-4241 and log on. (New users must set up an account; this is free.) Type SS/DI_SIG to select the Design Ideas section, RK1554 to select this idea, and D for downloading the file. Select protocol, download the file, log off, and then "unzip" the file.

A related idea appeared in the 7/7/94 issue of EDN.
(Circle 4)


[^1]Figure 1. The connections shown enable this $\mu C$ to substitute an external 12-bit A/D converter for its internal 8-bit converter. Replacing the external converter with the resistor network causes the $\mu C$ to resume use of its internal converter.

## DESIGN SHOWCASE

## Sine-wave generator is crystal accurate

Servos, test equipment, and telecommunications systems are among the applications that require stable, frequency-accurate sine-wave sources. Many such sine-wave oscillators are available, but finding one with a satisfactory level of absolute accuracy and drift can be a problem.

You can get greater accuracy and less drift by deriving the sine wave from a digital source. Because square waves comprise a fundamental at the square-wave frequency plus an infinite number of odd harmonics,


Figure 1. Filtering the harmonics from a square wave produces a sinusoidal output whose stability and flexibility derive from digital circuitry.
input signal ( $1 \mathrm{MHz} / 256$ ) falls within the flat portion of the filter response. Fifty-percent duty cycles on the IC2 outputs assure a symmetrical sine-wave output. The filter's major pole, or corner frequency, is fixed with respect to the clock and forms an internal clock-to-corner ratio of 100:1. Filter attenuation lowers the third-harmonic amplitude to -80 dB .
The output of the switched-capacitor filter resembles a sampled sine wave; to smooth it you can build a 1 st- or (as shown) a 2nd-order lowpass filter around the otherwise-uncommitted output op amp.
Because the filter's input and clock frequencies have a fixed ratio of $1: 128$, switching or sweeping the
frequency applied at C1 has a proportional effect on the sine-wave generator output. Switching this frequency from 2 MHz to 500 kHz , for example, switches the output frequency from 7812 Hz to 1953 Hz . Output amplitude is not affected because this band is well below the smoothing filter's 25 kHz corner frequency. Alias frequencies are not a problem, because the frequencies that represent a potential cause of aliasing in this circuit-the oddnumbered harmonics that exceed half the clock rate-have insignificant amplitudes.

A related idea appeared in the 7/25/94 issue of Electronic Design.

## 500Msps, 8-bit flash ADC delivers 7.0 effective bits at Nyquist

- 1.2 GHz input bandwidth
- 2ps aperture uncertainty

The MAX101, Maxim's first ultra-highspeed, ECL-compatible A/D converter, accurately digitizes analog signals from dc to the 250 MHz Nyquist frequency. Fabricated with Maxim's proprietary and advanced bipolar process, it contains a highperformance track/hold amplifier (T/H) and two flash quantizers, which produce their outputs alternately at separate 8 -bit ports.

Innovative $\mathrm{T} / \mathrm{H}$ design assures an input bandwidth of 1.2 GHz with an aperture uncertainty of less than 2 ps , resulting in 7.0 effective bits of resolution at the Nyquist frequency. Special decoding circuitry and comparator-output design reduce the probability of erroneous codes due to metasta-
bility, resulting in less than one error per $10^{15}$ clock cycles (equivalent to 500 Msps , 24 hours per day for 23 days).

The MAX101's analog input accommodates single-ended or differential signals in the range $\pm 270 \mathrm{mV}$. Sense pins for the reference voltage allow full-scale calibration and also aid in ratiometric operation. Other inputs let you adjust the converters' relative sampling times, and (by phasing the clock signals) you can interleave two or more devices to achieve higher sampling rates.

For less demanding applications, the MAX100 (containing one flash converter instead of two) guarantees a sampling rate of 250Msps.

MAX100/MAX101 converters are suitable for use in radar, high-speed imaging, instrumentation, and transient-event analysis. Both come in 84-pin ceramic flatpack packages, tested for operation over the commercial $\left(0^{\circ} \mathrm{C}\right.$ to $\left.+70^{\circ} \mathrm{C}\right)$ temperature range.
(Circle 6)

New spec guarantees boost performance of CMOS analog multiplexers
Guaranteed min/max limits assure unprecedented performance for Maxim's new CMOS analog multiplexers: MAX306/ MAX307 (16-channel single-ended, 8 -channel differential) and MAX308/ MAX309 (8-channel single-ended, 4-channel differential). Each device guarantees on-resistances less than $100 \Omega$, with no two channels differing by more than $5 \Omega$ maximum. In addition, each channel's onresistance is guaranteed flat within $7 \Omega$ over the specified analog signal range.

Fabricated with Maxim's 44V silicongate process, the new multiplexers sport design improvements that enhance performance in other ways as well. For example, the guaranteed low charge injection of 10 pC maximum yields excellent sample/hold circuits, and the low leakage over temperature minimizes source-resistance errors (MAX306/MAX307 $\mathrm{I}_{\mathrm{NO}(\text { OFF })}$ at $+85^{\circ} \mathrm{C}$ is less than 2.5 nA , and $\mathrm{I}_{\mathrm{COM}(\mathrm{OFF})}$ at $+85^{\circ} \mathrm{C}$ is less than 20 nA ).

Fast switching has not been sacri-ficed-the transition time for MAX306/ MAX307 multiplexers is less than 250ns. All devices are guaranteed (per MIL-STD883, Method 3015.7) to withstand electrostatic discharge (ESD) in excess of 2 kV .

All four multiplexers guarantee fast switching and TTL/CMOS compatibility while operating with single supplies of 4.5 V to 30 V or bipolar supplies of $\pm 4.5 \mathrm{~V}$ to $\pm 20 \mathrm{~V}$. The CMOS digital inputs reduce loading on digital control lines. These improved Maxim multiplexers are plug-in upgrades for industry-standard devices: the MAX306 and MAX307 replace DG406/DG407 and DG506A/DG507A multiplexers; the MAX308 and MAX309 replace DG408/ DG409 and DG508A/DG509A multiplexers.

MAX306/MAX307 devices come in 28pin 600-mil DIPs, PLCCs, and wide-SO packages; the MAX308/MAX309 devices come in 16-pin DIPs and narrow-SO packages. All are available in versions tested for the commercial $\left(0^{\circ} \mathrm{C}\right.$ to $\left.+70^{\circ} \mathrm{C}\right)$, extended-industrial $\left(-40^{\circ} \mathrm{C}\right.$ to $\left.+85^{\circ} \mathrm{C}\right)$, and military $\left(-55^{\circ} \mathrm{C}\right.$ to $\left.+125^{\circ} \mathrm{C}\right)$ temperature ranges. Prices start at $\$ 3.87$ for the MAX306/MAX307 and $\$ 2.50$ for the MAX308/MAX309 (1000 up, FOB USA).
(Circle 7)

## Ultra-fast 12-bit DAC updates at 300Msps

The monolithic MAX555, an ECLcompatible 12 -bit D/A converter, is fabricated with a proprietary, 9 GHz , oxideisolated bipolar process that guarantees minimum update rates of 300 Msps . The converter's complementary $50 \Omega$ voltage outputs and low output capacitance ( 15 pF ) enable it to drive $50 \Omega$ transmission lines directly.

The MAX555 is suitable for direct digital synthesis, arbitrary waveform generation, instrumentation, and video reconstruction. Operating from a single -5.2 V supply, it multiplies the applied digital input (interpreted as a fraction between 0 and 1) times the nominal 1 V analog reference signal. Usable bandwidth for the reference input is 10 MHz .

Precision laser trimming on the wafer yields 12-bit accuracy, with integral and differential linearity guaranteed to $\pm 1 / 2$ LSB ( $\pm 0.012 \%$ of full scale). Absolute gain error is $1 \%$ of full scale, and full-scale transitions occur in less than 0.5 ns . Laser trimming also assures precision $50 \Omega$ complementary outputs.

On-chip registers and decoding circuitry assure a low glitch energy of 5.6 pV -s. The MAX555 achieves precise RF performance over a spurious-free dynamic range of 70 dBc (at 50 Msps and $\mathrm{f}_{\text {OUT }}=3.125 \mathrm{MHz}$ ) or 54 dBc (at 250 Msps and $f_{\text {OUT }}=12.625 \mathrm{MHz}$ ).

MAX555 devices are screened for the commercial temperature range $\left(0^{\circ} \mathrm{C}\right.$ to $+70^{\circ} \mathrm{C}$ ), and they come in 68 -pin thermally enhanced PLCC packages capable of accepting a heatsink (the operating power dissipation is 900 mW ). Prices start at \$68.00 (100 up, FOB USA).
(Circle 8)


## Low-dropout linear regulators deliver 500 mA from 1.8 W SO package

The MAX603 and MAX604 linear regulators generate 5 V and 3.3 V respectively for load currents to 500 mA . Available in new, $1.8 \mathrm{~W}, 8$-pin SO packages, they feature low dropout voltages $(320 \mathrm{mV}$ at 5 V and 500 mA , or 240 mV at 3.3 V and $200 \mathrm{~mA})$, and low quiescent currents ( $15 \mu \mathrm{~A}$ typical, $35 \mu \mathrm{~A}$ maximum). Shutdown mode reduces the supply currents to less than $2 \mu \mathrm{~A}$.

In addition to preset outputs, both devices allow the user to set any output voltage between 1.3 V and 11 V using two external resistors (Dual Mode ${ }^{\text {TM }}$ operation). An internal protection scheme limits the reverse current when $\mathrm{V}_{\text {IN }}$ falls below $\mathrm{V}_{\text {OUT }}$, and the regulator outputs are protected by foldback current limiting and thermal-overload circuitry. The input range is 2.7 V to 11.5 V .

The pass transistor in MAX603/ MAX604 regulators (a p-channel MOSFET) allows them to draw less than $35 \mu \mathrm{~A}$ over temperature regardless of output current. Supply currents remain low because the

MOSFET-unlike the pnp pass transistor in a conventional regulator-requires no base current for operation. MAX603/MAX604 regulators also avoid the problem that plagues pnp regulators as $\mathrm{V}_{\text {IN }}$ approaches $\mathrm{V}_{\text {OUT }}$, when the pass transistor saturates and draws excessive base current.

MAX603/MAX604 devices come in 8pin DIPs and the new 1.8 W SO packages, in versions tested for the commercial $\left(0^{\circ} \mathrm{C}\right.$ to $+70^{\circ} \mathrm{C}$ ) and extended-industrial $\left(-40^{\circ} \mathrm{C}\right.$ to $+85^{\circ} \mathrm{C}$ ) temperature ranges. Prices start at \$1.68 (1000 up, FOB USA).
(Circle 9)
${ }^{\text {TM }}$ Dual Mode is a trademark of Maxim Integrated Products.

## Controller IC integrates core power-supply functions

The monolithic MAX781 controller integrates the core power-supply functions found in a PDA (personal digital assistant) or other wireless computer. It includes dual PCMCIA analog controllers, a $3.3 \mathrm{~V} \mathrm{~V}_{\mathrm{CC}}$ output, a programmable battery charger, five high-side gate drivers for external MOSFETs, and an SPI serial interface-all in a 36 -pin SSOP. The MAX781 input range ( 5 V to 18 V ) accommodates NiCd and NiMH battery stacks ranging from five to eight cells.

## 10A synchronous step-down controllers are $95 \%$ efficient

The MAX796/MAX797/MAX799 step-down dc-dc converters provide the main power for latest-generation CPUs in notebook and subnotebook computers, PDAs, mobile communicators, cellular phones, and other battery-powered systems. The combination of synchronous rectification (an active MOSFET in place of a passive Schottky diode) and Maxim's proprietary Idle-Mode ${ }^{\mathrm{TM}}$ control scheme results in efficiencies as high as $95 \%$. The outputs deliver as much as 10A.

Each device produces a main output of 5 V or 3.3 V , or an adjustable output of 2.5 V to 6 V set by two external resistors. The inputvoltage range ( 4.5 V to 30 V ) enables use of wall-adapter chargers and NiCd battery packs of up to 15 cells. For operation with 12 V in and 5 V out, the typical quiescent current is $375 \mu \mathrm{~A}$. The excellent dynamic response

To produce 3.3V, the internal step-down dc-dc converter employs synchronous rectification in a PWM (pulse-width modulation) switching scheme. The circuit's all nchannel design saves space and cost. The PWM switching frequency is fixed at 300 kHz to minimize noise in sensitive communications applications, and the synchronous rectification provides $92 \%$ conversion efficiency at full load. In shutdown, the device maintains an active 3.3 V output while lowering the 1 mA quiescent current to just $100 \mu \mathrm{~A}$.

The MAX781 provides control for the PCMCIA $\mathrm{V}_{\mathrm{CC}}$ and dual $\mathrm{V}_{\mathrm{PP}}$ outputs: $\mathrm{V}_{\mathrm{CC}}$ can be switched between $0 \mathrm{~V}, 3.3 \mathrm{~V}$, and 5 V ,
and the $\mathrm{V}_{\mathrm{PP}}$ outputs can be switched between $0 \mathrm{~V}, \mathrm{~V}_{\mathrm{CC}}$, and 12 V (also generated and regulated by the MAX781). Finally, the MAX781 includes a programmable current source for charging batteries. It operates in conjunction with a built-in multiplexer, which lets you implement custom charging algorithms by monitoring the battery's temperature, voltage, and charging current.

The MAX781 comes in a 36 -pin SSOP, in versions tested for the commercial $\left(0^{\circ} \mathrm{C}\right.$ to $\left.+70^{\circ} \mathrm{C}\right)$ and extended-industrial $\left(-40^{\circ} \mathrm{C}\right.$ to $+85^{\circ} \mathrm{C}$ ) temperature ranges. Prices start at $\$ 8.80$ (1000 up, FOB USA).
(Circle 10)
corrects output transients within five cycles of the 300 kHz clock. In addition, the internal bootstrap circuits provide gate drive for inexpensive n-channel external MOSFETs.

For dual-output, external-transformer applications, the MAX796 and MAX799 have an extra feedback terminal (SECFB) that enables regulation of a second output voltage derived from the transformer's secondary. The MAX796 produces a positive auxiliary voltage and the MAX799 produces a negative one. These secondary outputs can be used to program flash memories, power $3.3 \mathrm{~V} / 5 \mathrm{~V}$ systems, or provide an LCD-contrast supply. The independent secondary feedback path also minimizes cross-regulation problems for these auxiliary regulated voltages.

The MAX797 has a fixed-frequency PWM operating mode that reduces noise and RF interference in sensitive applications such as mobile communications and penentry systems. An override input ( $\overline{\mathrm{SKIP} \text { ) }}$ allows automatic switchover to Idle-Mode
operation at light loads (for high-efficiency pulse skipping). As an alternative, $\overline{\text { SKIP }}$ can force the converter to the low-noise fixedfrequency mode for all load conditions.

All devices provide a precision 2.505 V reference output, PWM operation at 300 kHz or 150 kHz , a synchronizing input, programmable soft-start capability, and $1 \mu \mathrm{~A}$ typical shutdown currents. The data sheet includes component lists and recommended suppliers for applications ranging from 1A to 10A. And to speed designs, Maxim offers pre-assembled evaluation kits (MAX796 EVKIT-SO and MAX797EVKIT-SO).

MAX796/MAX797/MAX799 converters are available in 16-pin DIP and narrow-SO packages, in versions tested for the commercial $\left(0^{\circ} \mathrm{C}\right.$ to $\left.+70^{\circ} \mathrm{C}\right)$ and extended-industrial $\left(-40^{\circ} \mathrm{C}\right.$ to $\left.+85^{\circ} \mathrm{C}\right)$ temperature ranges. Prices start at $\$ 3.65$ (1000 up, FOB USA).
(Circle 11)

[^2]
# NEW PRODUCT $S$ 

## 2A step-down controllers draw only $100 \mu \mathrm{~A}$

The MAX1649 and MAX1651 dc-dc step-down controllers are at least $90 \%$ efficient for loads between 10 mA and 1.5 A . They supply load currents as high as 2 A , and they accept inputs from 3 V to 16.5 V . Their low quiescent and shutdown currents ( $100 \mu \mathrm{~A}$ and $5 \mu \mathrm{~A}$ maximum, over temperature) conserve battery life. Each device controls an external p-channel switching MOSFET capable of a $96.5 \%$ maximum duty cycle, which drops only 300 mV for a 500 mA load.

The controllers employ current limiting and pulse-frequency modulation (PFM) with switching frequencies as high as 300 kHz . The resulting small inductor $(47 \mu \mathrm{H})$ and small external capacitors save space and cost. The devices offer fixed regulated outputs of 5 V (MAX1649) and 3.3V (MAX1651). They also provide adjustable outputs in the range 1.5 V to $\mathrm{V}_{\mathrm{IN}}$.

The MAX1649 and MAX 1651 are suitable for hand-held computers, personal communicators, and any other application for which small size and long battery life are critical. An evaluation kit (MAX649 EVKIT-SO) is available to speed your designs. Both controllers are available in 8pin DIP and SO packages, in versions tested for the commercial $\left(0^{\circ} \mathrm{C}\right.$ to $\left.+70^{\circ} \mathrm{C}\right)$ and extended-industrial $\left(-40^{\circ} \mathrm{C}\right.$ to $\left.+85^{\circ} \mathrm{C}\right)$ temperature ranges. Prices start at $\$ 1.60$ (1000 up, FOB USA).
(Circle 12)


## 6-bit quadrature digitizer provides 5.3 effective bits at 60 MHz

The monolithic, bipolar MAX2101 performs quadrature demodulation, 6-bit A/D conversion, and other functions for simple receiver subsystems. Applications include the recovery of PSK- and QAMmodulation, direct-broadcast satellite (DBS) systems, television receive-only (TVRO) systems, cable television (CATV) systems, and wireless local-area networks (WLANs). First developed as a custom integrated circuit for TV/COM, the MAX2101 provides an RF-to-bits function that bridges the gap between existing RF downconverters and CMOS digital signal processors (DSPs).

The MAX2101 accepts input signals in the range 400 MHz to 700 MHz , with a variable gain that provides up to 40 dB of dynamic range. At $\mathrm{f}_{\mathrm{IN}}=15 \mathrm{MHz}$ and $\mathrm{f}_{\text {SAMPLE }}=60 \mathrm{MHz}$ it produces an effective resolution greater than 5.3 bits. The internal local oscillator, phase-locked to an external crystal-stabilized standard, generates the 600 MHz (nominal) signal from which

## 12V/adjustable, step-up switching controller is 90\% efficient

The MAX1771 step-up switching controller provides $90 \%$ efficiency for load currents ranging from 30 mA to 2 A . Its control scheme-pulse-frequency modulation with current limiting-delivers the benefit of PWM control (high efficiency with heavy loads) while drawing less than $110 \mu \mathrm{~A}$ of supply current. (Typical PWM converters draw 2 mA to 10 mA .) The shutdown current is only $5 \mu \mathrm{~A}$.

High switching frequencies (to 300 kHz ) allow the MAX1771 to operate with miniature external components. The inductor, for example, is a surface-mount device only 5 mm high and 9 mm in diameter. The chip controls an external $n$-channel
quadrature components are derived. Mixed with the input signal, these components produce the internal baseband-video signals $I$ and Q .

The baseband signals are fed to separate 5th-order Butterworth lowpass anti-aliasing filters, and then to separate 6-bit A/D converters. (Users can substitute external filters.) The 60 Msps baseband sample rates can be varied by an on-chip programmable counter. Similarly, external control can vary the anti-aliasing filter bandwidths from 10 MHz to 30 MHz .

Other features include the auto-cancellation of dc offsets in the I and Q basebandvideo signals, and an on-chip divide-by-16 prescaler for the phase-locked quadrature components. (Further division may be required to meet the external reference frequency; that division is performed externally to avoid on-chip feedthrough to the baseband.)

The MAX2101 comes in a 100-pin MQFP package, screened for the commercial $\left(0^{\circ} \mathrm{C}\right.$ to $\left.+70^{\circ} \mathrm{C}\right)$ temperature range. Prices start at $\$ 17.95$ ( 1000 up, FOB USA).
(Circle 13)

MOSFET that can deliver 24 W to a load. For lower-power applications, consider a step-up switching regulator with on-board MOSFET, such as the MAX756, MAX757, MAX761, or MAX762.

MAX1771 output voltage is preset to 12 V , but can also be adjusted with two external resistors. The input-voltage range is 2 V to 16.5 V . A single current-limit threshold of 100 mV for all load conditions reduces noise and enhances efficiency at low input voltages.

The MAX1771 comes in 8-pin DIP and SO packages, in versions tested for the commercial $\left(0^{\circ} \mathrm{C}\right.$ to $\left.+70^{\circ} \mathrm{C}\right)$, extendedindustrial $\left(-40^{\circ} \mathrm{C}\right.$ to $\left.+85^{\circ} \mathrm{C}\right)$, and military $\left(-55^{\circ} \mathrm{C}\right.$ to $\left.+125^{\circ} \mathrm{C}\right)$ temperature ranges. Prices start at $\$ 1.80$ ( 1000 up, FOB USA). To speed your designs, request an evaluation kit (MAX770EVKIT-SO plus MAX1771CSA sample).
(Circle 14)


[^0]:    ${ }^{\mathrm{TM}}$ SPI and QSPI are trademarks of Motorola Inc.

[^1]:    STANDARD RESISTOR PACK DIP/SO $100 \Omega, \times 10$
    (SUBSTITUTING THIS PACKAGE FORIC1 ACTIVATES THE ADC INTERNAL TO IC2)

[^2]:    ${ }^{\text {TM }}$ Idle Mode is a trademark of Maxim Integrated Products.

